

The 2003 Bam (Iran) earthquake – rupture of a blind strike-slip fault

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An M_w 6.5 earthquake devastated the town of Bam in southeast Iran on 26 December 2003. Surface displacements and decorrelation effects, mapped using Envisat radar data, reveal that over 2 m of slip occurred at depth on a fault that had not previously been identified. It is common for earthquakes to occur on blind faults which, despite their name, usually produce long-term surface effects by which their existence may be recognised. However, in this case there is a complete absence of morphological features associated with the seismogenic fault that destroyed Bam.

1. Introduction

Bam lies within the western of two north-south, strike-slip fault systems located on each side of the aseismic Lut desert (Figure 1), which together accommodate the relative motion between central Iran and Afghanistan, part of the Eurasian plate [Jackson and McKenzie, 1988]. The town lies to the east of the Gowk fault on which several large earthquakes have occurred over the past 23 years [Berberian *et al.*, 1984; Berberian and Qorashi, 1994; Berberian *et al.*, 2001]. However, there are no recorded historical earthquakes at Bam, which was for about five hundred years on a flourishing trade route linking Persia with Sistan and Baluchistan [Ambraseys and Melville, 1982; Berberian and Yeats, 1999]. Most of the citadel, which was destroyed in the earthquake, dated from the Safavid period (1491–1722) [Matheson, 1976].

In the immediate aftermath of the earthquake, attention focused on faults whose surface traces, running north-south between Bam and Baravat, are clearly visible on satellite imagery (Figure 1). Field surveys that we carried out in the week after the earthquake found no major surface rupture but showed small-scale fissuring along the fault trace south of the Posht-rud river, and along a 5 km lineament north of the river (Figure 2a,b). The northern fault cuts across a featureless plain and is consistent with pure strike-slip faulting. The southern fault appears consistent with a north-south striking, westward-dipping blind thrust fault [e.g. Lettis *et al.*, 1997].

These observations suggested that rupture had occurred at depth on the faults associated with the surface traces. However, in the following section we show an interferogram derived from the first co-seismic pair of images obtained by the Advanced Synthetic Aperture Radar (ASAR) on the ESA Envisat spacecraft to become available after the earthquake. The surprising result is that the main rupture in the earthquake did not occur on faults beneath the obvious surface traces, but on a fault further west, in a region where there is

a complete absence of surface features (Figure 1). This fault lies immediately south of Bam and extends directly beneath the city at its northern end.

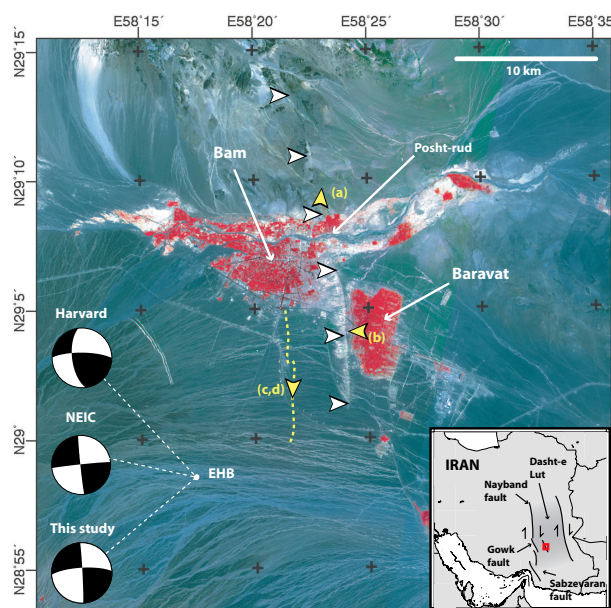


Figure 1. ASTER false colour image of the epicentral region. Red colours indicate the presence of vegetation in the cities of Bam and Baravat (labelled). Focal mechanisms from Harvard, NEIC and this study¹ are shown; the EHB epicentre is provided by E. R. Engdahl (unpublished data, 2004). [White arrowheads: locations of the previously-identified Bam Fault; yellow arrowheads: locations and viewing direction of field photographs in Figure 2; yellow dashed line: surface trace of the newly-revealed blind strike-slip fault responsible for this earthquake.] Inset: location of this area within Iran (red box), with locations of the Nayband-Gowk-Sabzevaran fault system and Dasht-e Lut (Lut desert).

2. Interferometric observations of the Bam earthquake

Since the launch of ERS-1 in 1991, Interferometric Synthetic Aperture Radar interferometry (InSAR) has become a widely used technique for mapping the deformation of the earth's surface caused by earthquakes [e.g. Massonnet and Feigl, 1998]. We processed a pair of descending-track ASAR images spanning the earthquake with a time separation of 35 days – the shortest possible repeat time for Envisat – and improved the effective baseline of the resultant interferogram by differencing with a second interferogram constructed from a pre-seismic pair of ASAR images¹ [Massonnet and Feigl, 1998; Table 1]. The topographic contribution to the phase in each interferogram was removed using a digital elevation model (DEM) constructed from an ERS tandem pair (Table 1).

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Figure 2. Field observations of surface faulting features. Locations and orientations of the photographs are given in Figure 1. (a) Surface rupture north of Bam with en-echelon pattern; (b) Cracking at the foot of the ridge visible in the ASTER image west of Baravat; (c) View southward over en-echelon patterns of surface rupture on the main seismogenic fault south of Bam; (d) Close-up at the locality shown in (c), with right lateral displacement of ~ 20 cm.

The interferogram (Figure 3a) shows an asymmetric, four-lobed pattern, centred on a north-south oriented discontinuity that is coincident with an incoherent band in the interferogram. The eastern lobes are larger in magnitude than those in the west, with the south-east quadrant moving towards the satellite by ~ 30 cm, and the north-east quadrant moving away from the satellite by ~ 16 cm. West of the discontinuity, the phase changes are smaller, with a range decrease of ~ 5 cm in the NW and range increase of ~ 5 cm in the SW. These range changes represent, we believe, the coseismic displacement due to the earthquake – although we cannot rule out the possibility of rapid postseismic deformation, we expect such an effect to be small; an interferogram spanning the interval between 12 and 47 days after the earthquake shows less than 2 cm of range change in the vicinity of Bam (unpublished data, 2004).

To further investigate the discontinuity evident in the interferogram, we calculated the interferometric correlation¹, a measure of the spatial similarity of radar returns (amplitude and phase) in the interferogram. If the distribution of radar-reflective objects inside a SAR resolution cell changes between the two image acquisitions, the correlation will be reduced. Despite the long spatial baselines, the correlation in the interferograms is generally high, probably due to the low relief, arid environment and short temporal separation. However, the correlation image (Figure 3c) shows that the city of Bam and town of Baravat have a very low degree of correlation. Part of this decorrelation is caused by vegetation – Bam and Baravat are important regional producers of dates and citrus fruits. The remainder is due to the high degree of damage sustained in Bam

during the earthquake, with more than 50% of the buildings in the city destroyed or badly damaged.

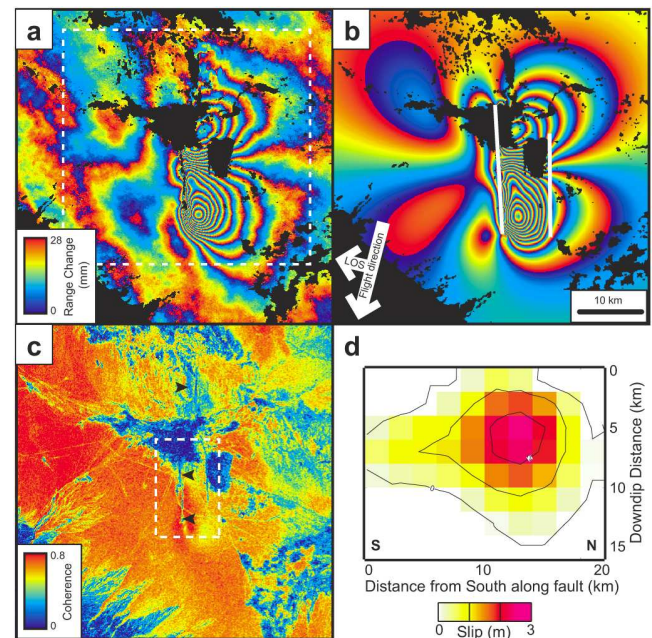


Figure 3. (a) Detail of Envisat ASAR interferogram. [White dotted box: area shown in Figure 1.] (b) Synthetic interferogram of the same area based upon our best-fitting two-fault distributed-slip model. [White lines: surface projections of model fault planes; white arrows: direction of motion of the satellite and pointing direction of the radar antenna.] (c) Interferometric correlation (coherence). [Red colours: high correlation; blue colours: low; black arrows: location of band of low coherence due to surface faulting; white dotted box: location of the enlargements in Figure 4.] (d) The distribution of slip on the main right-lateral strike-slip fault.

The correlation image also reveals several narrow, linear bands of very low correlation, both north and south of Bam (Figures 3c and 4a); similar features have been shown to represent fault surface ruptures in previous earthquakes [e.g. *Simons et al.*, 2002]. In the north, there is an area of decorrelation coincident with the minor surface ruptures described earlier (Figure 2a). The decorrelation feature south of Bam was not mapped in our original field survey, but aligns with the largest discontinuity in the interferometric phase. Prompted by this discovery, we carried out further field work in this area. We found a series of discontinuous en echelon surface breaks, each 50–100 m long, trending at N 30° E (Figure 2c,d) and aligned along the decorrelated band (Figure 4a). The maximum observed offset was 20 cm in a right-lateral sense, with a slip vector that was typically oriented at N 10° E.

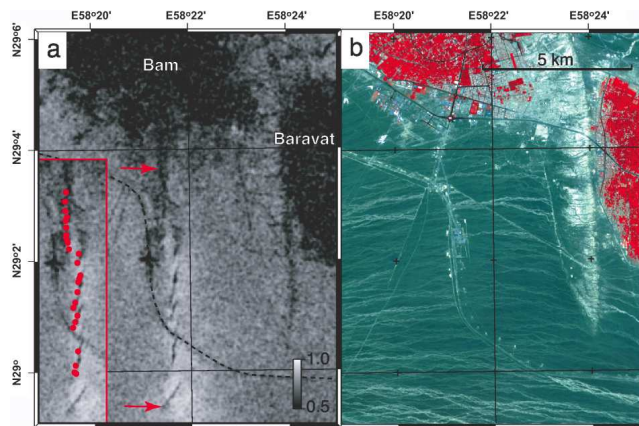


Figure 4. (a) Detail of interferometric correlation south of Bam. The dashed line marks the trace of the railway line that can also be seen in (b). Inset: locations of observed surface breaks plotted over correlation image, showing that they coincide with the black incoherent features. (b) Enlargement of ASTER image for the same area as (a), demonstrating the absence of surface features above the Bam earthquake fault. The previously-identified Bam Fault is easily visible at the right of the image.

3. Determining fault parameters using InSAR

Preliminary seismic focal mechanisms for the earthquake (Figure 1) suggested that it involved predominantly strike-slip motion on a near-vertical fault. To determine a source mechanism from the interferogram, we modeled the co-seismic displacements with slip on a rectangular dislocation in an elastic half space [Okada, 1985]. We used a non-linear inversion algorithm [Wright *et al.*, 1999] to solve for the strike, dip, rake, slip, dimensions, location and depth of the fault. To start with, we inverted for uniform slip on a single fault but found that a near-vertical fault, consistent with the NEIC mechanism based on first motions, and with a surface trace located at the linear zone of decorrelation discussed above, leaves large unmodeled decreases in range south of Bam.

If a second, thrust fault is introduced beneath the previously-mapped Bam fault, 5 km to the east of the main rupture (Figure 1), an improved fit to the interferogram is obtained in the area where the single fault model leaves significant residuals. The introduction of a secondary fault is supported by modeling of teleseismic P- and SH-bodywaves¹ which suggests there was a second event ~10 seconds after the mainshock, with about 20% of the seismic moment of the main strike-slip event and consistent with a north-south thrust dipping west at ~30° (Auxiliary Figures 1–3¹). In addition, strong motion records from an accelerometer in Bam suggest a second event, showing a broad displacement pulse at 8–10 seconds after the first arrivals (BHRC, Iran, <http://www.bhrc.gov.ir/Bhrc/d-strgrmo/shabakeh/earthquake/bam/bam.htm>). In calculating the

model interferogram we fix the values of strike, dip and rake for the main, strike-slip event (357°, 88°, -166°) and the secondary, thrust fault (180°, 30°, 90°) to the values obtained by seismology¹.

To determine a more realistic picture of the slip on the faults at depth, we solved for the best-fitting, smooth distribution of slip on the fault planes (Figure 3b,d), having extended them spatially in all directions¹. A good fit to data is obtained, with far-field residuals at the level of atmospheric noise (Auxiliary Figure 4d¹). For the strike-slip fault we find that most slip occurred over a region that is 12 km long and 8 km wide, with a peak slip of 2.5 m at a depth of ~5 km, decaying to a maximum of 0.5 m in the upper 2 km – consistent with our field observations which showed that only a small amount of slip reached the surface (Figure 2c,d). Errors in these slip estimates¹ are ≤ 0.2 m in the upper 10 km of the fault (Auxiliary Figure 5¹). The secondary, thrust fault slipped up to 1.2 m at depth between the southern end of the main, strike-slip fault, and the previously-mapped Bam Fault. Although non-unique and preliminary, this solution is consistent with both InSAR and seismological observations.

Table 1. Interferograms constructed for this study

	sensor 1	date 1	sensor 2	date 2	B _⊥ ^a
preseismic	ASAR	11-Jun-03	ASAR	03-Dec-03	480 ^b
coseismic	ASAR	03-Dec-03	ASAR	07-Jan-04	540 ^b
DEM	ERS-1	02-Apr-96	ERS-2	03-Apr-96	-129

^a Perpendicular baseline (metres).

^b In this study, these interferograms were differenced to form a composite image with an effective baseline of 60 m.

4. Discussion

The main strike-slip fault revealed by InSAR has no surface expression in satellite imagery acquired before the earthquake (Figure 4). Field photographs (Figure 2c) show that the area is a largely featureless plain cut by small drainage channels. It is estimated that the Nayband-Gowk-Sabzevaran fault system only accommodates about 1–2 mm/yr of the 15 mm/yr relative motion between central Iran and Afghanistan [Walker and Jackson, 2002]. As these faults, to the west of Bam, are more pronounced morphologically, it is likely that the strain rate on the fault that failed in the Bam earthquake is only a very small fraction of this total. Given a long likely recurrence interval it is possible that the surficial features of past earthquakes on this fault, likely to be of similar size to those of the 2003 event, will have been obscured by sedimentation – either from infrequent floods or from wind-blown deposits – leaving no trace of the fault at the surface.

Identifying seismogenic faults is a key component of seismic hazard analysis. In the case of buried, or ‘blind’ faults, it becomes of critical importance. Earthquakes on blind thrust faults are not uncommon, e.g. Tabas, Iran (1978), Northridge, California (1994). Even if there is no historical record of past earthquakes, a blind thrust will produce geomorphological effects that can be recognised, such as drainage incising into topography produced by the thrusting [e.g. Lettis *et al.*, 1997; Walker *et al.*, 2003]. The strike-slip fault at Bam, however, is completely blind – in the absence of an earthquake, no feature in the topography or drainage pattern would have alerted us to its presence. The combination of an absence of any historical reports of past earthquakes at Bam, and the absence of surface features produced by past faulting on the main fault, makes estimating the seismic hazard in such an area extremely difficult.

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Notes

1. Auxiliary figures and explanations of methods are available at <ftp://ftp.agu.org/apend/gl/2004GL020058>.

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